

## Some bureaucracy before moving on

$X \uplus Y \triangleq X \otimes \mathbf{1} \cup Y \otimes \mathbf{2}$  where

- ▶  $\mathbf{n} \triangleq \{n\}$  for any natural number  $n$
- ▶  $f \otimes \mathbf{n} \triangleq \{(x, n) \mapsto f(x) \mid x \in X\}$  for any  $f$  on  $X$
- ▶  $R \otimes \mathbf{n} \triangleq \{((x, n), (y, n)) \mid (x, y) \in R\}$  for any relation  $R \subseteq X \times Y$

Given a pomset  $r = [\mathcal{E}, \leq, \lambda]$ , let  $\mathcal{E}_{r, \mathbf{A}} \subseteq \mathcal{E}$  denote the set of events labelled with actions performed by  $\mathbf{A}$ .

The pomset of  $\mathbf{A}$  in  $r$  is

$$r|_{\mathbf{A}} = [\mathcal{E}_{r, \mathbf{A}}, \leq \cap (\mathcal{E}_{r, \mathbf{A}} \times \mathcal{E}_{r, \mathbf{A}}), \lambda|_{\mathcal{E}_{r, \mathbf{A}}}]$$

## Well-sequencedness, formally

Let  $r = [\mathcal{E}, \leq, \lambda]$  and  $r' = [\mathcal{E}', \leq', \lambda']$  and define

$$\begin{aligned} \text{seq}(r, r') &= [\mathcal{E} \uplus \mathcal{E}', \leq_{\text{seq}}, (\lambda \otimes \mathbf{1}) \cup (\lambda' \otimes \mathbf{2})] \\ \leq_{\text{seq}} &= \left( (\leq \otimes \mathbf{1}) \cup (\leq' \otimes \mathbf{2}) \cup \bigcup_{A \in \mathcal{P}} ((\mathcal{E}_{r, A} \times \mathbf{1}) \times (\mathcal{E}_{r', A} \times \mathbf{2})) \right)^* \end{aligned}$$

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Two g-choreographies  $G, G' \in \mathcal{G}$  are **well-sequenced** if

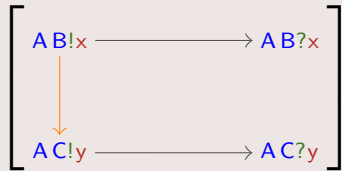
- ▶  $\llbracket G \rrbracket \neq \text{undef}$
- ▶  $\llbracket G' \rrbracket \neq \text{undef}$ , and
- ▶  $ws(r, r')$  for all  $r \in \llbracket G \rrbracket, r' \in \llbracket G' \rrbracket$

where  $ws(r, r')$  if

- ▶ for all  $e' \in \mathcal{E}'$  s.t.  $\lambda'(e') = AB!m \in \mathcal{E}$ , if there is  $e \in \mathcal{E}$  s.t.  $\lambda(e) = AB?m$  then  $e \leq_{\text{seq}} e'$
- ▶ and  $\leq_{\text{seq}(r, r')} \supseteq (\{e \in \mathcal{E} \mid \lambda(e) \in \mathcal{L}^!\} \times \mathbf{1}) \times (\{e \in \mathcal{E}' \mid \lambda'(e) \in \mathcal{L}^?\} \times \mathbf{2})$

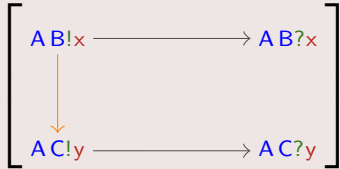
# Well-sequencedness at work

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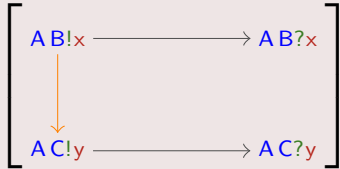


$$r = \left[ \begin{array}{cc} \text{sbj A} & \text{sbj B} \end{array} \right]$$

$$r' = \left[ \begin{array}{cc} \text{sbj A} & \text{sbj B} \end{array} \right]$$

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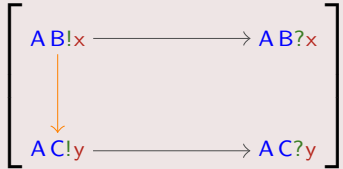
$$r = \left[ \begin{array}{cc} \text{subj A} & \text{subj B} \end{array} \right]$$

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$$\text{seq}(r, r') = \left[ \begin{array}{cc} \text{subj A} & \text{subj B} \\ \text{subj A} & \text{subj B} \end{array} \right]$$

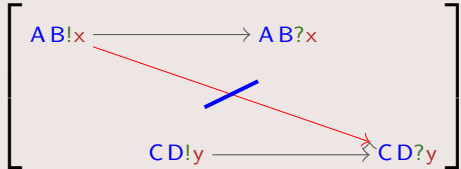
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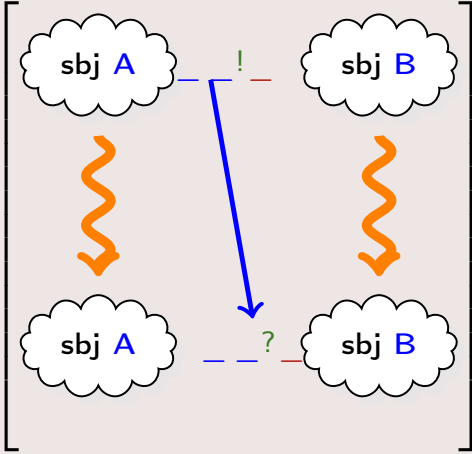
$A \rightarrow B: x; C \rightarrow D: y$

No minimal input "from the continuation"



(and no output in the continuation interfering with "left-inputs")

$ws(r, r')$



## Well-branchedness: an intuition

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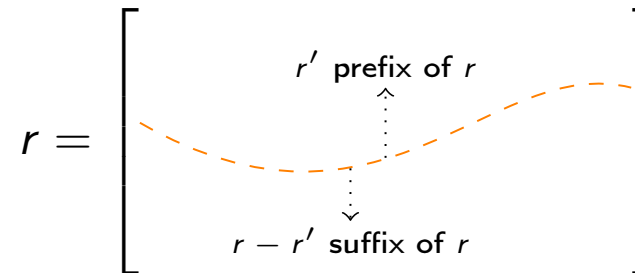
- ▶ there should be **at most one active** participant
- ▶ any non-active participant should be **passive**

non-standard

standard

**Problem:** Participants do not necessarily “enter” a choice “immediately”

**An idea:** find a “common part” of the branches for which participants behave uniformly in  $G_1$  and  $G_2$



## Prefix maps & divergence points

The pair of functions  $(\phi, \psi)$  is an **A-prefix map of  $G_1$  and  $G_2$**  if

- ▶  $\text{dom } \phi = \text{dom } \psi$  is a partition of  $\llbracket G_1 \rrbracket \downarrow_A$  and  $\text{cod } \phi$  is a partition of  $\llbracket G_2 \rrbracket \downarrow_A$
- ▶  $\phi$  is bijective and  $\text{cod } \psi$  is a set of pomsets

s.t. for all  $R \in \text{dom } \phi$  and  $(r, r') \in R \times \phi(R)$ , the pomset  $\psi(R)$  is a prefix  $r$  and  $r'$ .

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The **divergence point of  $G_1$  and  $G_2$  with respect to the A-prefix map  $(\phi, \psi)$**  is

$$\text{div}_{\phi, \psi}(G_1, G_2) = (L_1, L_2) \quad \text{where} \quad \begin{cases} L_1 = \bigcup_{R \in \text{dom } \phi} \bigcup_{r \in R} \lambda_r(\min(r - \psi(R))) \\ L_2 = \bigcup_{R \in \text{cod } \phi} \bigcup_{r \in R} \lambda_r(\min(r - \psi(\phi^{-1}(R)))) \end{cases}$$

# Active & passive components

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- ▶ **A** is **active** in  $G_1 + G_2$  if there exists an **A**-prefix map  $(\phi, \psi)$  of  $G_1$  and  $G_2$  with divergence point  $\text{div}_{\phi, \psi}(G_1, G_2) = (L_1, L_2)$  s.t.
  - ▶  $L_1 \cup L_2 \subseteq \mathcal{L}!$
  - ▶  $L_1 \neq \emptyset$  and  $L_2 \neq \emptyset$
  - ▶  $L_1 \cap L_2 = \emptyset$

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- ▶ **A** is **passive** in  $G_1 + G_2$  if there exists an **A**-prefix map  $(\phi, \psi)$  of  $G_1$  and  $G_2$  with divergence point  $\text{div}_{\phi, \psi}(G_1, G_2) = (L_1, L_2)$  s.t.
  - ▶  $L_1 \cup L_2 \subseteq \mathcal{L}?$
  - ▶  $L_1 = \emptyset \iff L_2 = \emptyset$
  - ▶  $L_2 \cap \lambda_r(\mathcal{E}_{r-\psi(R)}) = \emptyset$  for all  $R \in \text{dom } \phi$  and  $r \in R$
  - ▶  $L_1 \cap \lambda_r(\mathcal{E}_{r-\psi(\phi^{-1}(R))}) = \emptyset$  for all  $R \in \text{cod } \phi$  and  $r \in R$

## Class test

Figure out the graphical structure of the following terms and for each of them say which one is well-branched

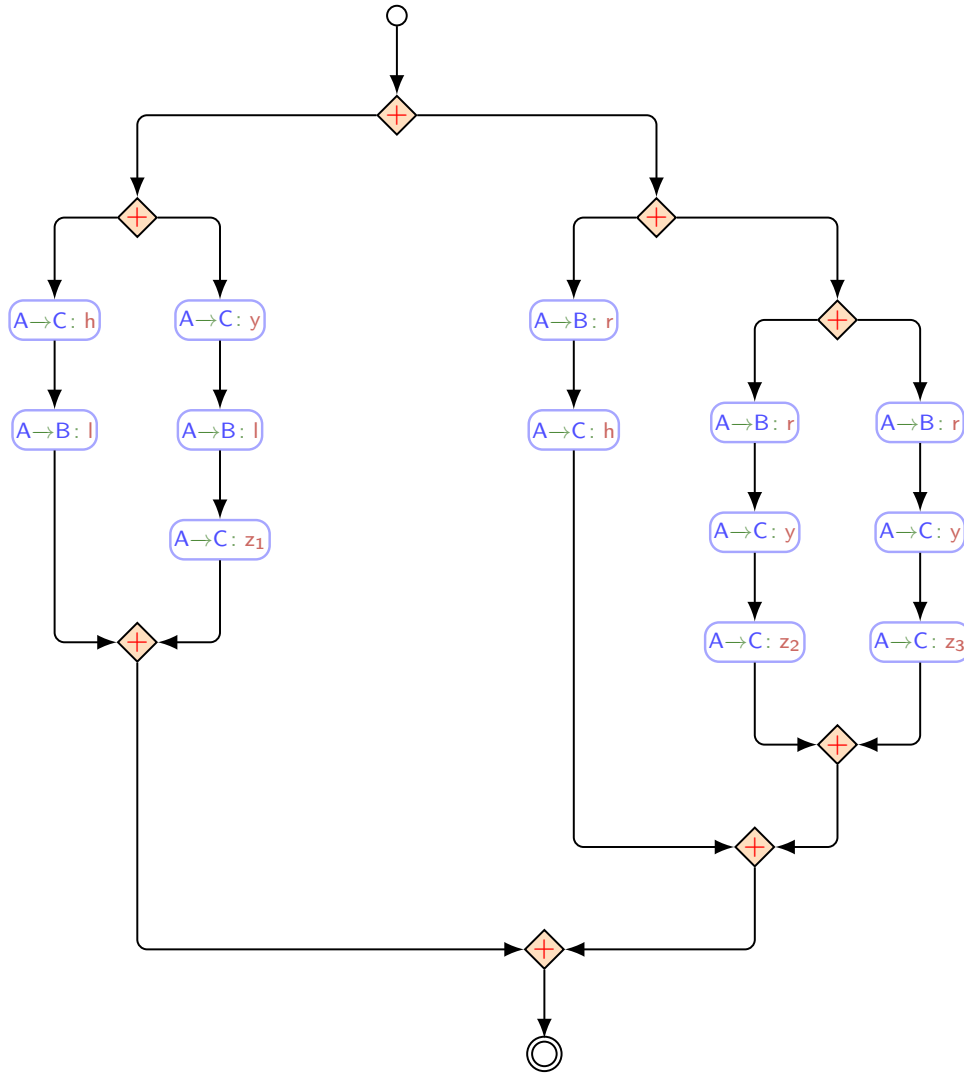
▶  $G_1 = A \rightarrow B: \text{int} + A \rightarrow B: \text{str}$

▶  $G_2 = A \rightarrow B: \text{int} + \odot$

▶  $G_3 = A \rightarrow B: \text{int} + A \rightarrow C: \text{str}$

▶  $G_4 = \left( \begin{array}{l} A \rightarrow C: \text{int}; A \rightarrow B: \text{bool} \\ + \\ A \rightarrow C: \text{str}; A \rightarrow C: \text{bool}; A \rightarrow B: \text{bool} \end{array} \right)$

# $G_{\text{sad}}$ : a difficult choice



$G_{\text{sad}} = G_1 + G_2$  where

$$G_1 = \left( \begin{array}{l} A \rightarrow C: h; A \rightarrow B: l \\ + \\ A \rightarrow C: y; A \rightarrow B: l; A \rightarrow C: z_1 \end{array} \right)$$

$$G_2 = A \rightarrow B: r; A \rightarrow C: h + G_{2a} + G_{2b}$$

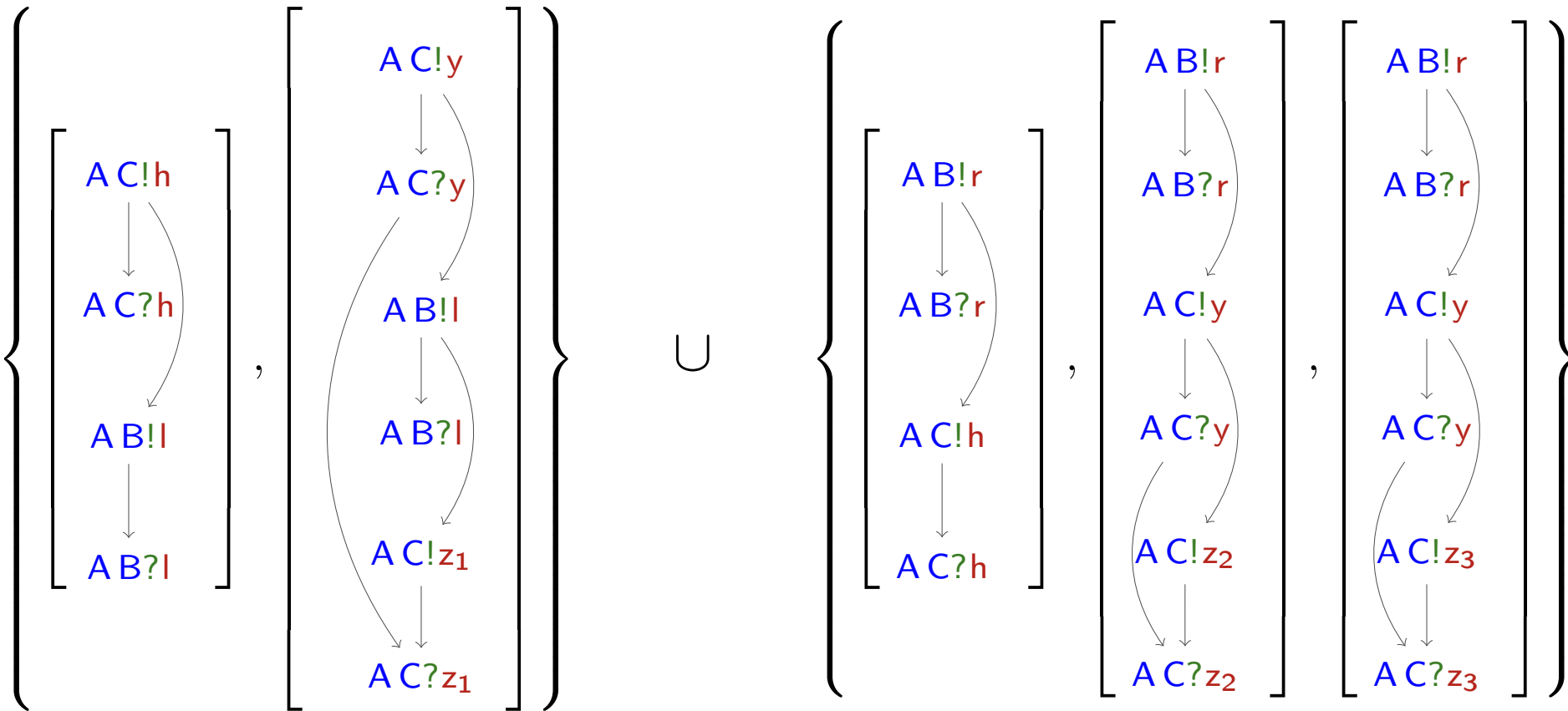
$$G_{2a} = A \rightarrow B: r; A \rightarrow C: y; A \rightarrow C: z_2$$

$$G_{2b} = A \rightarrow B: r; A \rightarrow C: y; A \rightarrow C: z_3$$

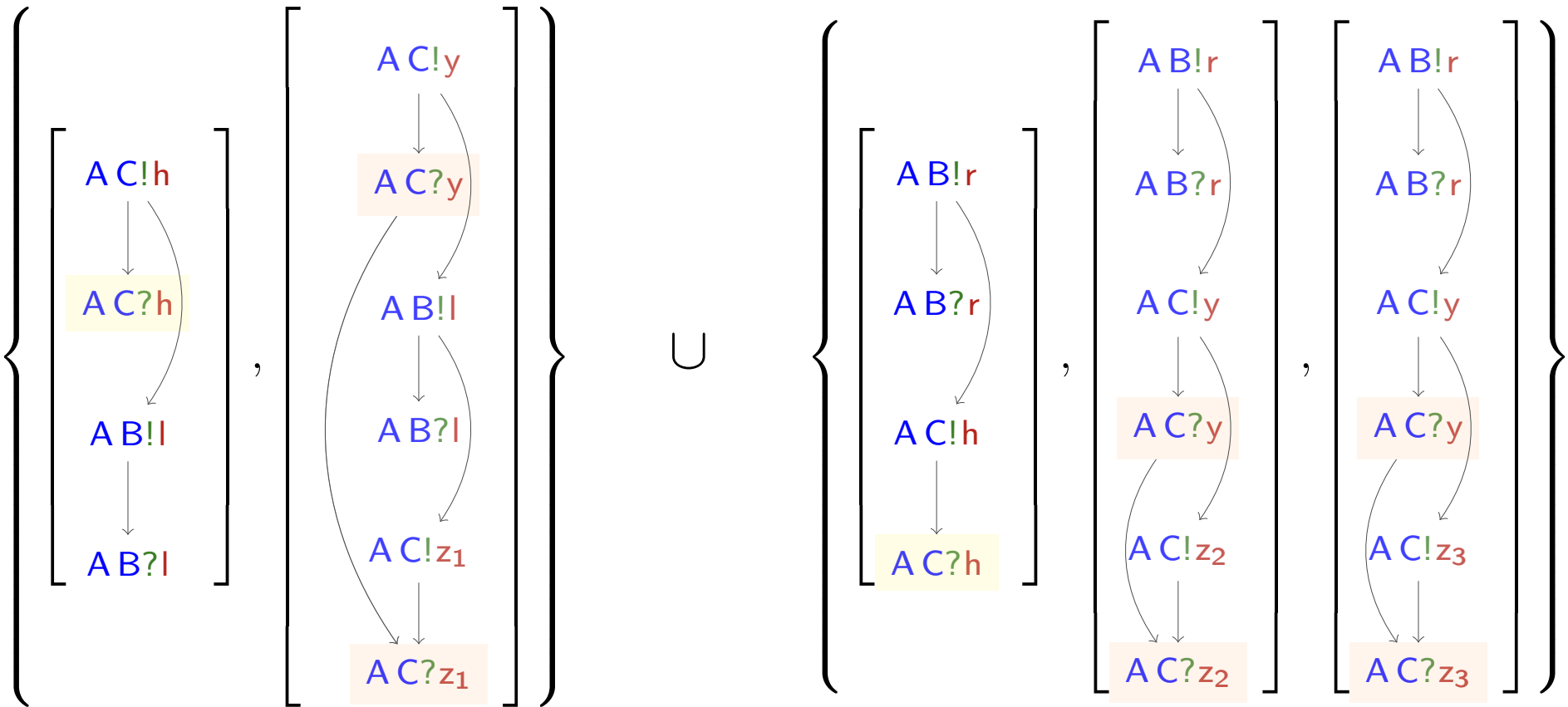
A chooses ... and

- ▶ Whatever B gets, he won't know if A and C exchanged or not h
- ▶ If C gets h, he won't know if A and B exchanged l or r

# The pomsets of G 😊



# The pomsets of $G_{\text{smiley}}$ ...from $C$ 's point of view



# Communicating systems [2]

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A tuple  $M = (Q, q_0, \rightarrow)$  is a **communicating finite-state machine** (CFSM) if

- ▶  $Q$  is a finite set of *states* with  $q_0 \in Q$  the **initial** state, and
- ▶  $\rightarrow \subseteq Q \times \mathcal{L} \times Q$ ; we write  $q \xrightarrow{l} q'$  for  $(q, l, q') \in \rightarrow$

$M$  is **A-local** if for each  $q \xrightarrow{l} q'$   $\left\{ \begin{array}{l} \text{either } l = BA?m \\ \text{or } l = AB!m \end{array} \right.$  for some  $B \in \mathcal{P}$  and  $m \in \mathcal{M}$

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A **configuration** of  $S$  is a pair  $s = \langle \vec{q} ; \vec{b} \rangle$  where

- ▶  $\vec{q} = (q_A)_{A \in \mathcal{P}}$  with  $q_A$  a state of  $S(A)$
- ▶  $\vec{b} = (b_{AB})_{AB \in \mathcal{C}}$  with  $b_{AB} \in \mathcal{M}^*$

The **initial** configuration  $s_0$  is the one where, for all  $A \in \mathcal{P}$ ,  $q_A$  is the initial state of  $S(A)$  and  $b_{AB} = \varepsilon$  for all  $AB \in \mathcal{C}$

# Semantics of communicating systems

A configuration  $s' = \langle \vec{q}' ; \vec{b}' \rangle$  is *reachable* from another configuration  $s = \langle \vec{q} ; \vec{b} \rangle$  by **firing a transition**  $l$ , written  $s \xrightarrow{l} s'$ , if either of the following holds

1.  $l = AB!m$  and  $q_A \xrightarrow{l} q'_A$  and

a.  $q'_C = q_C$  for all  $C \neq A$  and

b.  $b'_{AB} = b_{AB}.m$  and

c.  $b'_{CD} = b_{CD}$  for all  
 $(C, D) \neq (A, B) \in \mathcal{C}$

2.  $l = AB?m$  and  $q_B \xrightarrow{l} q'_B$  and

a.  $q'_C = q_C$  for all  $C \neq B$  and

b.  $b_{AB} = m.b'_{AB}$  and

c.  $b'_{CD} = b_{CD}$  for all  
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## Special configurations

$s = \langle \vec{q} ; \vec{b} \rangle$  is **stable** if  $\vec{b} = \vec{\varepsilon}$ .

$s = \langle \vec{q} ; \vec{b} \rangle$  is a **deadlock** if  $s \not\rightarrow$  and there exists a participant  $A \in \mathcal{P}$  such that

$q_A \xrightarrow{AB?m} q'_A$

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