Another (important) variant of TS

A labelled transition system is a triple 
$$(S, A_1, \rightarrow)$$
 where  
- S is a set of states  
- A is a set of labels ( a actions, or operations, or events,...)  
-  $\rightarrow \subseteq S \times A \times S$  ( $\rightarrow : S \rightarrow Z^{A \times S}$ ) transition relation  
 $\frac{dservable}{dservable}$  information about  
 $\frac{dservable}{dservable}$  information  $\frac{dservable}{dservable}$  is a unit  
 $\frac{dservable}{dservable}$  is a unit of the transition  
 $\frac{dservable}{dservable}$  is a unit of the transition  

## Communication-based concurrency

A robotic scenario:

Some mobile robots need to manage their energy in order to accoplish their task (e.g., patrolling some premises).

- When their batteries deplete, robots look for a recharge.
- Recharges are offered by recharge stations or other robots.

We can model this behaviour using an LTS capturing the observable features we are interested in: in this case communication For instance, the behaviour of a robot seeking for a recharge is



Exercise 4 Give an LTS modelling the behaviour of a robot offering a recharge. Reflect about the "compatibility" between your solution and the LTS (\*) above Regular expressions

BNF. like squtax A, twite alphabet  

$$E:=0|1|a|E+E|E\cdotE|E^*$$
  
and  $Sign atomic fifther doe instruct.$   
Dendstional semantis:  $\mathcal{L}:E \longrightarrow 2^{A^*}$   
 $\mathcal{L}(0) = \emptyset \qquad \mathcal{L}(1) = 4E$   $\mathcal{L}(a) = 1at$   
 $\mathcal{L}(e_1+E_2) = \mathcal{L}(E_1) \cup \mathcal{L}(E_2)$   
 $\mathcal{L}(E_1, E_2) = \mathcal{L}(E_1) \cdot \mathcal{L}(E_2) \triangleq 1 \cup w \in A^* | w \in \mathcal{L}(E_1), w \in \mathcal{L}(E_2)$   
 $\mathcal{L}(E^*) = \mathcal{L}(E)^* = \bigcup \mathcal{L}(E)^m$ 

Exercise 6 Prove or disprove that  $(a + b)^* = (a^* + b^*)^*$